

Differential Equation Limits for Sparse Algorithms

INFORMS 2006 Markov Lecture Discussant:

R. W. R. Darling

National Security Agency, USA

Random Process Analogues of Two Basic Limit Theorems

	$1/\sqrt{N}$ SCALING	$1/N$ SCALING
Sum of N random variables	Central limit theorem	Large deviation bound
Random process, scale parameter N	Diffusion Limit <ul style="list-style-type: none">■ Ethier/Kurtz, '86■ Jacod/Shiryaev, '03	Exponential rate of convergence to ODE

Markov Process Dynamics

MARKOV JUMP PROCESS
IN OPEN SET $U \subset \mathbb{R}^d$

MARTINGALE SUBJECT
TO EXPONENTIAL INEQUALITY

COMPENSATOR
= DRIFT

Limiting Differential Equation

$$x_t = x_0 + \int_0^t b[x_s] ds$$

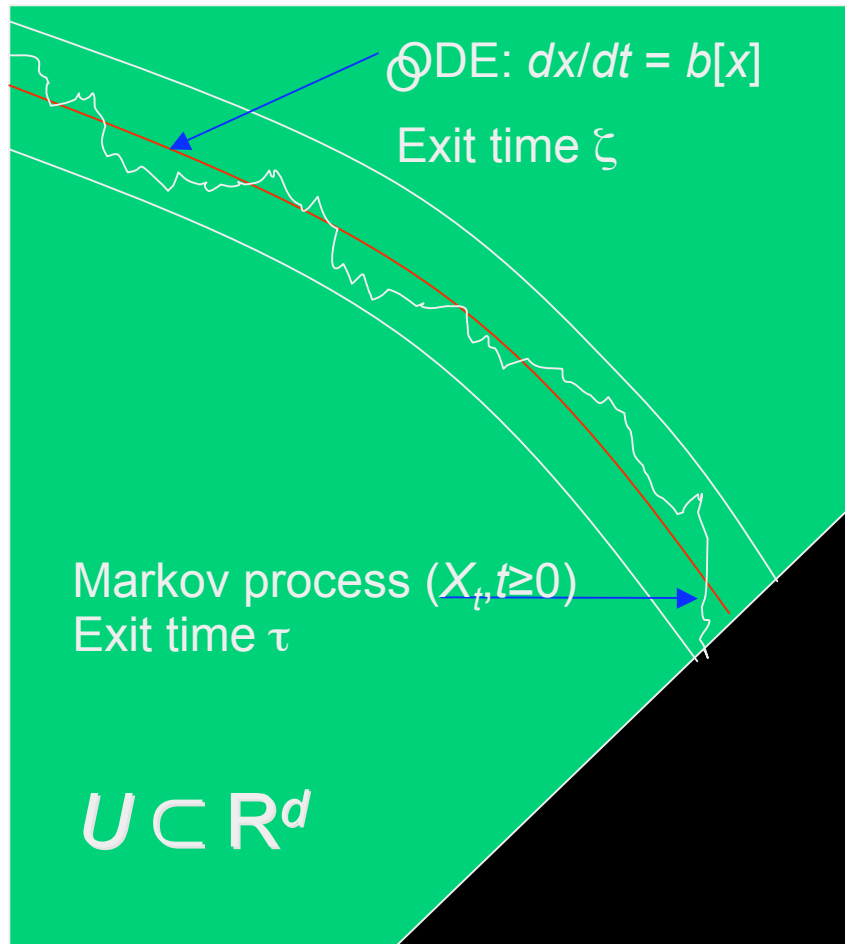
DETERMINISTIC
TRAJECTORY



LIPSCHITZ VECTOR FIELD
ON OPEN SET $U \subset \mathbb{R}^d$



Exit Probability from a Tube



- Jump size $O(1/N)$
- Jump rate $O(N)$
- Suppose ODE trajectory not tangential to boundary.
- Given bounds on β - b , & on exponential moments of M , both

$$\mathbf{P}[\sup_{t \leq T} \|X_t - x_t\| > \varepsilon],$$
 &

$$\mathbf{P}[\|X_\tau - x_\xi\| > \varepsilon]$$
 decay as $c_0 \exp[-cN]$,
for computable $c > 0$.

Models for Combinatorial Algorithms

- “I can simulate a combinatorial algorithm. Why build an analytic model?”
 1. The ODE has parameters which reveal analytically where phase transitions occur between solvable and unsolvable problems.
 2. A Markov model makes explicit the statistical assumptions about the problem’s structure.
 3. Predict behavior in cases too large to simulate.

Multipurpose Modeling Tool: Random Bipartite Graphs

GREEN NODES WITH PRESCRIBED DEGREES

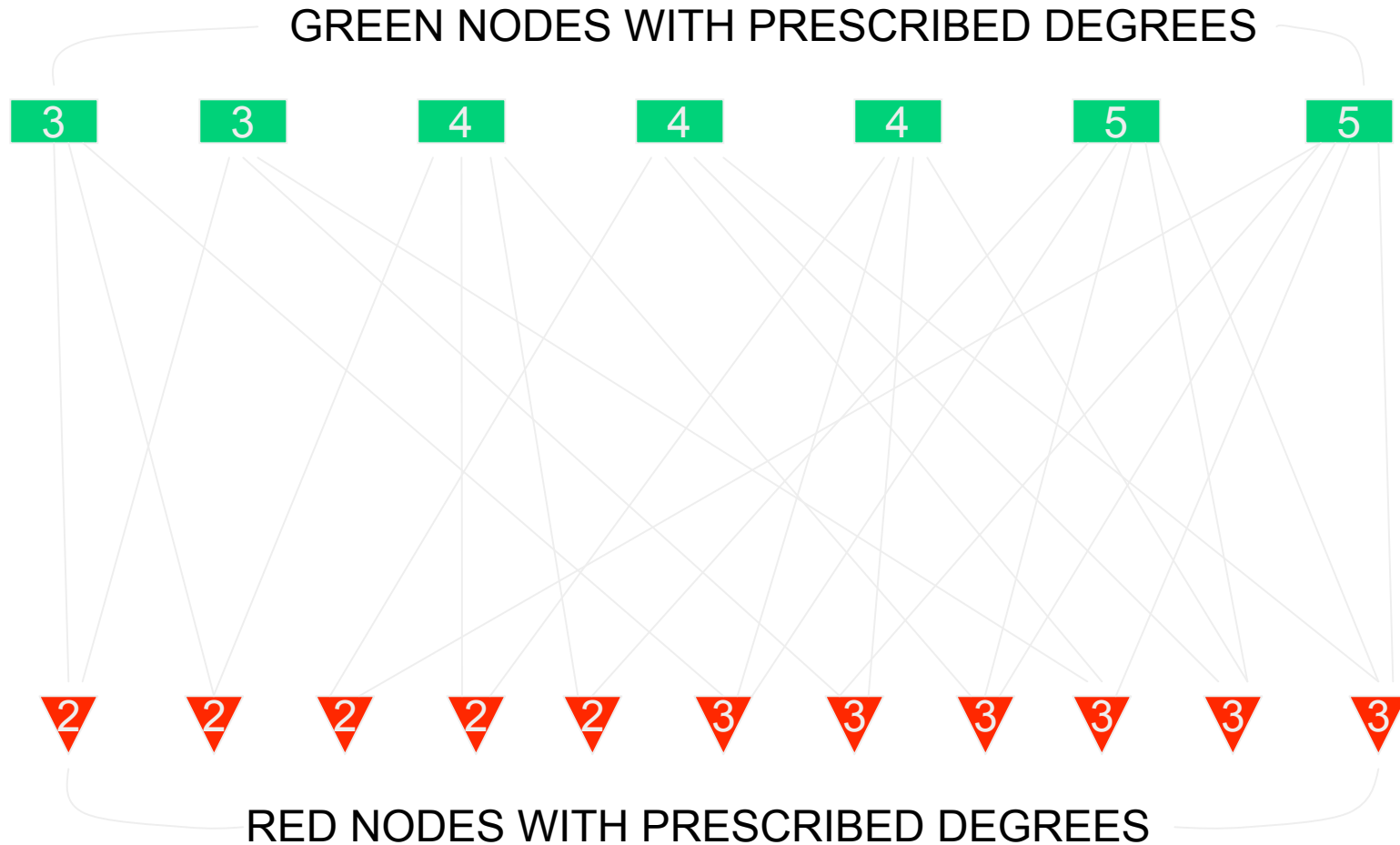


SAMPLE UNIFORMLY AT RANDOM FROM
BIPARTITE GRAPHS WITH THESE DEGREES



RED NODES WITH PRESCRIBED DEGREES

Random Bipartite Graph: Realization Under Degree Constraints



Bipartite Graph Interpretations

	GREEN NODE i	RED NODE k	EDGE $\{i, k\}$
LT Codes	Source symbol i	Coded symbol k	$i \in \{\text{inputsfor } k\}$
Boolean satisfiability	Boolean variable i	Logical clause k	$i \in \{\text{inputsfor } k\}$
Matching problems	Job i	Server k	k is able to perform i

Factor Graph Abstraction

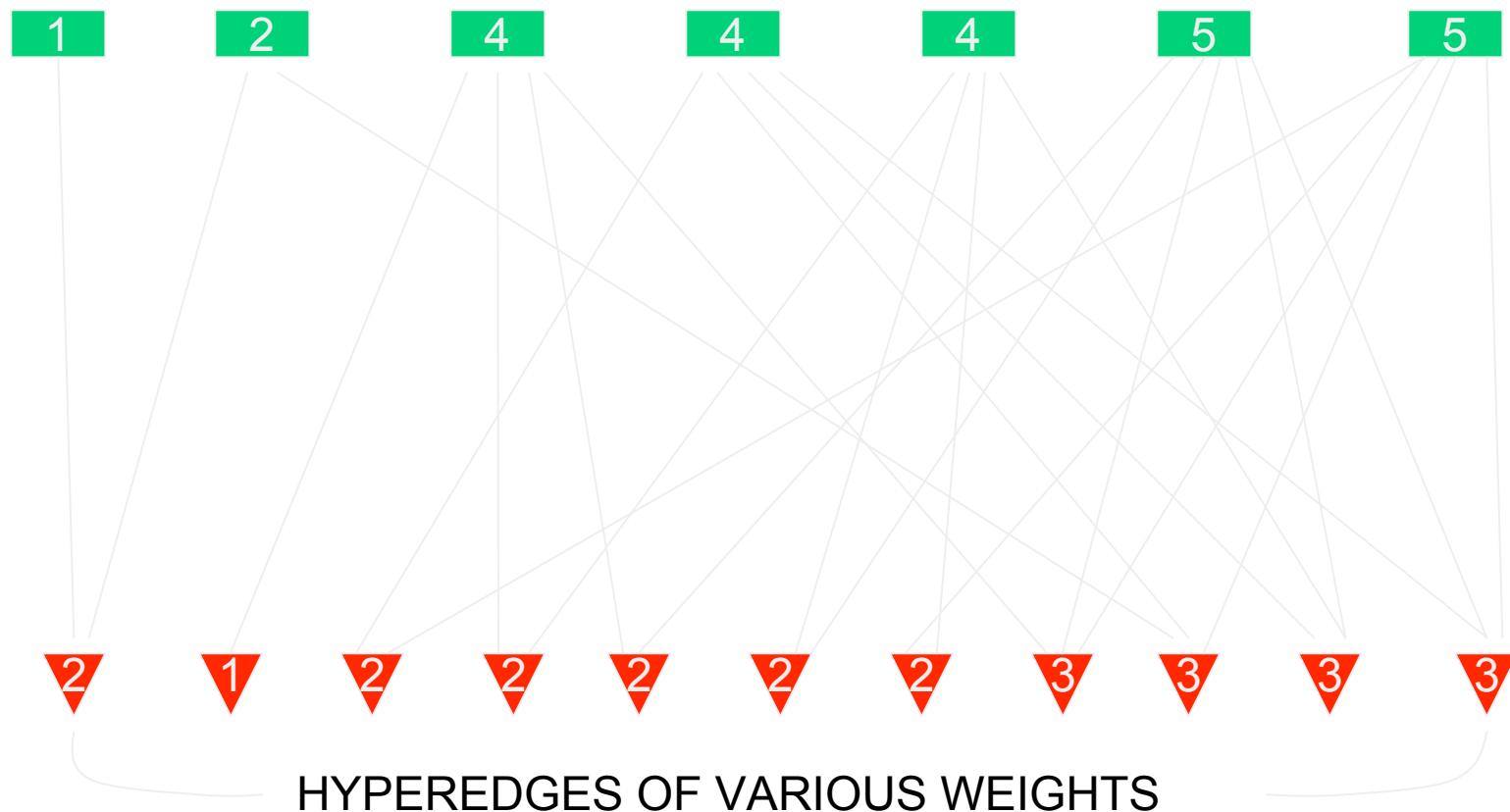
	GREEN NODE i	RED NODE k	EDGE $\{i,$ $k\}$
Hypergraph	Vertex $i \in V$	$E_k \subset V$ “hyperedge”	$i \in E_k$ “incidence”
Factor Graph <ul style="list-style-type: none"> ■ Aji & McEliece '00 ■ Kschischang, Loeliger & Frey '01 	Variable i	Function f_k	$\{\text{arguments of } f_k\} \ni i$

Examples of Algorithms Leading to Finite-Dimensional Markov Chains

1. Bipartite matching – Karp & Sipser '81
2. Random Walk Sat – Schöning '99
3. LT decoding via Hypergraph 2-Core –
Luby '00; Maneva & Shokrollahi '06; Hajek '06

Hypergraph 2-Core

Select at random an incidence touching a degree 1 vertex, if one exists; remove entire hyperedge.



Simplifying Principle (Core)

- Call a vertex of degree ≥ 2 “heavy”.
- After each hyperedge removal, restriction of hypergraph to the heavy vertices is still sampled uniformly, given its vertex degrees & edge weights.
- Hence a vector of vertex degrees, and a vector of edge weights, suffice to define “state” of Markov process.

Simplifying Principle (SAT)

- $X^{c,i} := |\text{clauses with } c \text{ correctly set, and } i \text{ incorrectly set variables}|.$
- $Y^{t,f} := |\text{variables appearing in } t \text{ TRUE and } f \text{ FALSE clauses}|.$
- Matrices $(X^{c,i})$ & $(Y^{t,f})$ are called marginals.
- If a SAT problem is uniformly distributed, given its marginals, then it remains so after each transition of Random Walk SAT.
- Hence $(X^{c,i})$ & $(Y^{t,f})$ serve as the state for a Markov process model of Random Walk SAT.

Further Reading

- Dimitris Achlioptas, *Lower bounds for random 3-SAT via differential equations*, '01.
- Luby, Mitzenmacher, Shokrollahi, *Analysis of random processes via AND-OR tree evaluation*, '98.
- R.W.R.D. & J.R. Norris: *Structure of large random hypergraphs*, '05.
- ..., *Differential equation approximations for Markov chains (Survey)** .
- ..., *Cores & cycles in random hypergraphs, I & II** .

* to be posted on ArXiv